

# Nonlinear Analysis of GaN MESFETs With Volterra Series Using Large-Signal Models Including Trapping Effects

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**Abstract**—Nonlinearities in GaN MESFETs are reported using a large-signal physics-based model. The model accounts for the observed current collapse to determine the frequency dispersion of output resistance and transconductance. Calculated  $f_T$  and  $f_{\max}$  of a  $0.8\ \mu\text{m} \times 150\ \mu\text{m}$  GaN MESFET are 6.5 and 13 GHz, respectively, which are in close agreement with their measured values of 6 and 14 GHz, respectively. A Volterra-series technique is used to calculate size and frequency-dependent nonlinearities. For a  $1.5\ \mu\text{m} \times 150\ \mu\text{m}$  FET operating at 1 GHz, the 1-dB compression point and output-referred third-order intercept point are 16.3 and 22.2 dBm, respectively. At the same frequency, the corresponding quantities are 19.6 and 30.5 dBm for a  $0.6\ \mu\text{m} \times 150\ \mu\text{m}$  FET. Similar improvements in third-order intermodulation for shorter gatelength devices are observed.

**Index Terms**—GaN MESFETs, large-signal modeling, Volterra series and intermodulation distortion.

## I. INTRODUCTION

RECENTLY, GaN-based devices are being pursued extensively for potential applications in high-power microwave circuitries. GaN with a bandgap of 3.4 eV and a breakdown field of 4 MV/cm allows GaN-based devices to operate with higher supply voltage to provide higher output power as compared to similar channel-length GaAs and Si FETs [1]. Besides, superior transport characteristics in terms of electron peak velocity ( $3 \times 10^7$  cm/s), saturation velocity ( $1.5 \times 10^7$  cm/s), low field mobility ( $1500\ \text{cm}^2/\text{V} \cdot \text{s}$ ) [2], and lower parasitic is suitable for high-frequency applications, as has recently been reported by Lu *et al.* [3], where  $f_T = 101$  GHz and  $f_{\max} = 155$  GHz were obtained with a  $0.12\ \mu\text{m} \times 100\ \mu\text{m}$  GaN/Al<sub>0.20</sub>Ga<sub>0.80</sub>N high electron-mobility transistor (HEMT). GaN grown on SiC offers a thermal conductivity of  $4.5\ \text{W}/\text{cm} \cdot \text{K}$ , making the system suitable for high-temperature and high-power applications. Consequently, output power of 9.8 W/mm at 8 GHz has been reported by Wu *et al.* [4] using a  $0.5\ \mu\text{m} \times 150\ \mu\text{m}$  Al<sub>0.38</sub>Ga<sub>0.62</sub>N/GaN HEMT. Moreover, Daumiller *et al.* [5] have reported GaN-based FETs with operating up to 750 °C.

With improved growth and fabrication techniques, device fabrication is progressing at a frantic pace. However, this has

not been followed by comparable effort in modeling. The optimization of the power-handling capability, especially at higher frequencies, requires nonlinear analysis using large-signal transistor models [6], [7]. Moreover, the large-signal device models used in microwave circuitries must include dc-to-RF dispersions of the device characteristics for accurate analysis of the analog- and mixed-signal and high-power circuits [8], [9]. The dispersion of the electrical characteristics, especially the device transconductance and output resistance, are due to the presence of traps in the structure. Recently, quite a few authors have reported the effect of traps on the current collapse in the dc current-voltage characteristics. Binari *et al.* [10] have demonstrated that the application of a moderately large drain bias (up to 10 V) did not result in current collapse in a GaN HEMT. However, the application of a drain bias exceeding 20 V results in current collapse in the subsequent measurements. A similar observation has been reported by Hsin *et al.* [11] for a GaN/InGaN heterojunction field-effect transistor (HFET). Current collapse is observed in the absence of light and is associated with the trapping of electrons at the channel/buffer interface [12]. Kunihiro *et al.* [13] have reported recovery of current collapse with measurements carried out with 10-s hold time, which relates trapping effects with the applied signal frequency and can be modeled by the frequency dispersion of device transconductance and output resistance [8], [9]. Based upon these observations, a mechanism to explain current collapse in GaN MESFETs is proposed and a physics-based model to incorporate dc-to-RF dispersion of transconductance and output resistance is developed [14], [15]. The dispersion frequency depends on the detrapping time constant and increases with increasing temperature. For GaN-based devices, dispersion frequency is of the order of hertz at room temperature; however, it increases to the megahertz range at 600 K [14]. Thus, the device transconductance and output resistance obtained at dc should be corrected to include the dispersion effects for microwave circuit analysis.

In this paper, nonlinearities in GaN MESFET have been analyzed using a Volterra-series technique. Volterra-series analysis, a frequency-domain technique, has been extensively used for nonlinear analysis of GaN HEMTs [6], GaAs MESFETs [16], and AlGaAs/GaAs heterojunction bipolar transistors (HBTs) [17]. A large-signal physics-based model is used in this analysis, which takes into account the frequency dispersion of transconductance and output resistance. The size dependence of 1-dB compression points ( $P_{1\text{-dB}}$ ), output-referred third-order

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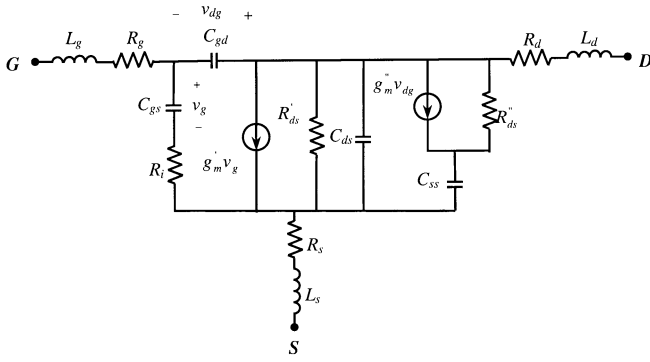


Fig. 1. GaN MESFET large-signal model. Linear model parameters are  $R_g = 6 \Omega$ ,  $L_g = 0.055 \text{ nH}$ ,  $R_d = 70 \Omega$ ,  $L_d = 0.307 \text{ nH}$ ,  $R_s = 90 \Omega$ ,  $L_s = 0.027 \text{ nH}$ ,  $R_i = 25 \Omega$ , and  $C_{ds} = 0.040 \text{ pF}$  [8], [12].

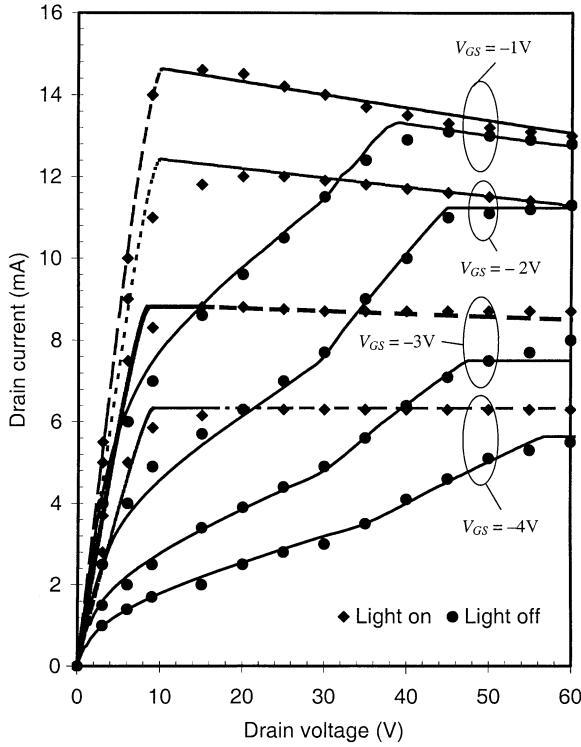


Fig. 2.  $I$ - $V$  characteristics considering trapping effects of the  $1.5 \mu\text{m} \times 150 \mu\text{m}$  GaN MESFET [12]. Calculated and measured results are shown by solid lines and symbols, respectively.

intercept points (OIP3s) and third-order intermodulation points (IM3s) is analyzed.

## II. ANALYSIS

The large-signal GaN MESFET circuit model is shown in Fig. 1. Following the treatment reported by Golio *et al.* [8],  $g'_m$ ,  $R'_{ds}$ , and  $C_{ss}$  are incorporated in the intrinsic MESFET equivalent circuit to account for the frequency dispersion of transconductance and output resistance due to traps. Expressions of these circuit parameters are given in the Appendix and are based upon the incorporation of traps to determine the current-voltage characteristics [14], [15]. In Fig. 2, the calculated  $I$ - $V$  characteristics for a  $1.5 \mu\text{m} \times 150 \mu\text{m}$  GaN MESFET [12] with channel thickness  $d = 2000 \text{ \AA}$ , channel doping  $N_d = 2 \times 10^{17} \text{ cm}^{-3}$ , trap concentration at the channel-buffer inter-

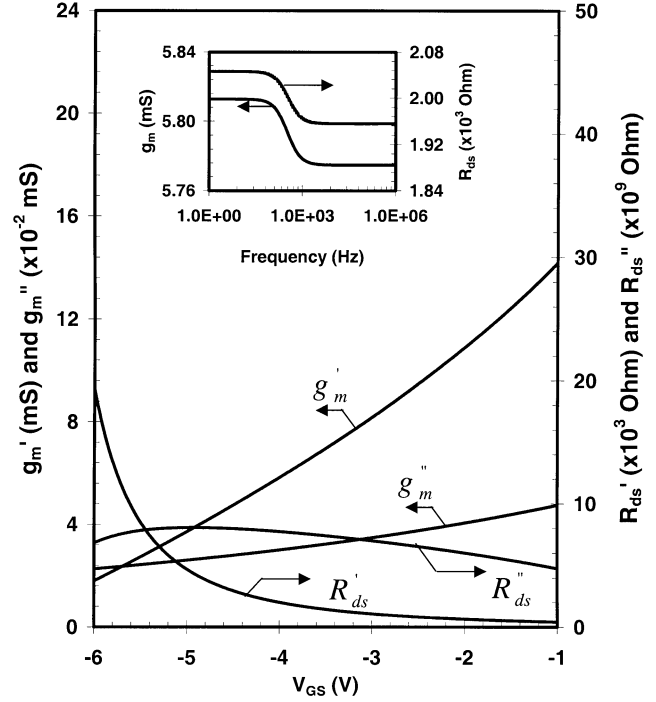


Fig. 3. Transconductances ( $g'_m$  and  $g''_m$ ) and resistances ( $R'_{ds}$  and  $R''_{ds}$ ) as a function of gate voltage with  $V_{DS} = 25 \text{ V}$  for the  $1.5 \mu\text{m} \times 150 \mu\text{m}$  GaN MESFET [12]. Inset shows the intrinsic transconductance ( $g_m$ ) and output resistance ( $R_{ds}$ ) as a function of frequency for  $V_{DS} = 25 \text{ V}$ ,  $V_{GS} = -4 \text{ V}$ , and  $t_d = 0.5 \text{ ms}$ .

face  $N_{to} = 1.5 \times 10^{16} \text{ cm}^{-3}$ , and low field mobility  $\mu_n = 410 \text{ cm}^2\text{V}^{-1}\text{s}^{-1}$  are shown. In this same figure, experimental results are also plotted to show good agreement. The agreement is achieved by assuming exponential decay of the occupied trap density in the form  $N_t = N_{to} \exp(-\alpha(V_{DS} - V_{DS}^{\text{ONSET}}))$ , where  $V_{DS}^{\text{ONSET}}$  is the drain bias at first pinchoff with all the traps being occupied and  $\alpha = 0.112 \text{ V}^{-1}$ .

Fig. 3 shows the variation of  $g'_m$ ,  $g''_m$ ,  $R'_{ds}$  and  $R''_{ds}$  as a function of gate bias for a  $1.5 \mu\text{m} \times 150 \mu\text{m}$  GaN MESFET at  $V_{DS} = 25 \text{ V}$  [12].  $g'_m$  and  $R'_{ds}$  follow variations of device transconductance and output resistance with gate bias typical to any standard MESFET. For a detrapping time constant  $t_d$  of  $0.5 \text{ ms}$  [14],  $R''_{ds}$  is of the order of  $10^9 \Omega$  and much higher than the other resistive components in the model. The variation of the overall intrinsic transconductance and output resistance with increasing frequency is shown as an inset in Fig. 3. At low frequency, the overall intrinsic transconductance  $g_m$  equals  $g'_m$ , whereas for frequencies greater than the dispersion frequency,  $f_{o(gm)} = 1/2\pi C_{ss} R''_{ds}$ ,  $g_m$  approaches  $g'_m - g''_m$ . For frequencies lower than  $f_{o(rds)} = 1/2\pi t_d$ , the overall output resistance approaches  $R'_{ds}$  and becomes  $R'_{ds} || R''_{ds} || 1/g''_m$  for frequencies greater than  $f_{o(rds)}$  [14]. The other intrinsic circuit parameters are obtained by conventional small-signal MESFET analysis.

For large-signal analysis,  $g_m$ ,  $g_{ds}$ , and  $C_{gs}$  are considered nonlinear functions of  $v_g$ , while  $C_{gd}$  is nonlinear function of  $v_{dg}$ . The nonlinear functions are approximated up to the second-order term  $p = p_0 + p_1 v + p_2 v^2$ , where  $p$  represents  $g_m$ ,  $g_{ds}$ ,  $C_{gs}$ , or  $C_{gd}$  and  $v$  represents  $v_g$  or  $v_{dg}$ . The coefficients  $p_0$ ,  $p_1$ , and  $p_2$  are shown in Table I for  $L \times 150 \mu\text{m}$  GaN MESFETs at  $V_{DS} = 25 \text{ V}$ .

TABLE I  
NONLINEAR MODEL PARAMETERS FOR  $L \times 150 \mu\text{m}$  GaN MESFETs ( $v_g$  OR  $v_{dg}$  ARE IN VOLTS AND  $V_{DS} = 25 \text{ V}$ ) [12]

	$L = 0.6 \mu\text{m}$	$L = 0.8 \mu\text{m}$	$L = 1.0 \mu\text{m}$	$L = 1.5 \mu\text{m}$
$g_{m0} (mS)$	43.4	32.5	26.0	17.3
$g_{m1} (mS.V^{-1})$	8.8	6.6	5.3	3.5
$g_{m2} (mS.V^{-2})$	0.40	0.30	0.24	0.16
$g_{ds0} (mS)$	8.5	6.4	5.1	3.4
$g_{ds1} (mS.V^{-1})$	2.7	2.0	1.6	1.1
$g_{ds2} (mS.V^{-2})$	0.21	0.16	0.13	0.09
$C_{gs0} (fF)$	133.6	178.2	222.7	334.1
$C_{gs1} (fF.V^{-1})$	25.0	33.4	41.7	62.5
$C_{gs2} (fF.V^{-2})$	2.10	2.80	3.50	5.25
$C_{gd0} (fF)$	21.5	28.7	35.9	53.8
$C_{gd1} (fF.V^{-1})$	-0.49	-0.66	-0.82	-1.23
$C_{gd2} (fF.V^{-2})$	0.005	0.007	0.009	0.013

Defining ports 1–5 across nonlinear elements  $C_{gs}$ ,  $g_m$  and  $g_{ds}$ ,  $C_{gd}$ , load and source, respectively, and terminating the source and load with impedances  $Z_S$  and  $Z_L$ , respectively, the elements of the  $5 \times 5$  system matrix  $Y$  are expressed as follows:

$$Y_{1,1}(\omega) = 1/R_i + j\omega C_{gs0} \quad (1)$$

$$Y_{1,2}(\omega) = Y_{1,3}(\omega) = Y_{3,1}(\omega) = -1/R_i \quad (2)$$

$$Y_{2,1}(\omega) = -1/R_i + g_{m0} \quad (3)$$

$$Y_{1,4}(\omega) = Y_{4,1}(\omega) = Y_{1,5}(\omega) = Y_{5,1}(\omega) = 0 \quad (4)$$

$$Y_{2,2}(\omega) = 1/R_i + \left[ \frac{1}{(R_d + j\omega L_d)} + \frac{1}{(Z_s(\omega) + R_g + j\omega L_g)} \right]^{-1} + j\omega C_{ds} + g_{ds0} \quad (5)$$

$$Y_{4,4}(\omega) = \left[ \frac{1}{(Z_s(\omega) + R_g + j\omega L_g)} + \frac{1}{(R_s + j\omega L_s)} \right]^{-1} + \frac{1}{R_d + j\omega L_d} + 1/Z_L(\omega) \quad (6)$$

$$Y_{5,5}(\omega) = \left[ \frac{1}{(R_s + j\omega L_s)} + \frac{1}{(R_d + j\omega L_d)} \right]^{-1} + Z_s(\omega) + R_g + j\omega L_g \quad (7)$$

$$Y_{2,5}(\omega) = Y_{5,2}(\omega) = -Y_{5,5}(\omega) \left[ \frac{(R_d + j\omega L_d)}{(R_s + j\omega L_s + R_d + j\omega L_d)} \right] \quad (8)$$

$$Y_{2,4}(\omega) = Y_{4,2}(\omega) = \left[ \frac{1}{Z_L(\omega)} - Y_{4,4}(\omega) \right] \times \left[ \frac{Z_s(\omega) + R_g + j\omega L_g}{R_s + j\omega L_s + Z_s(\omega) + R_g + j\omega L_g} \right] \quad (9)$$

$$Y_{3,4}(\omega) = Y_{4,3}(\omega) = \left[ Y_{4,4}(\omega) - 1/Z_L(\omega) \right] \times \left[ \frac{R_s + j\omega L_s}{R_s + j\omega L_s + Z_s(\omega) + R_g + j\omega L_g} \right] \quad (10)$$

$$Y_{2,3}(\omega) = Y_{3,2}(\omega) = 1/R_i - Y_{2,5}(\omega) \quad (11)$$

$$Y_{3,3}(\omega) = Y_{5,5}(\omega) + 1/R_i + j\omega C_{dg0} \quad (12)$$

$$Y_{3,5}(\omega) = Y_{5,3}(\omega) = -Y_{5,5}(\omega) \quad (13)$$

$$Y_{5,4}(\omega) = Y_{4,5}(\omega) = -Y_{3,4}(\omega). \quad (14)$$

With an applied signal of amplitude  $V_{s1}$  at frequency  $\omega_1$ , the first-order port voltages across ports 1–4 are determined by using the following matrix equation [18]:

$$[V_p(\omega_1)] = -[Y_{i=p,j=1,\dots,4}]^{-1} [Y_{i=p,j=5}]^T [V_{5,1} = V_{s1}], \quad p = 1, \dots, 4. \quad (15)$$

Second-order voltages  $V_p(\omega_1, \omega_2)$  appear across ports at mixing frequency  $\omega_1 + \omega_2$  when two tones are applied with amplitudes  $V_{s1}$  and  $V_{s2}$  at frequencies  $\omega_1$  and  $\omega_2$ , respectively. Second-order port voltages are calculated by applying nonlinear currents through each nonlinear port. The nonlinear currents are evaluated by using the first-order port voltages due to individual tones and  $p_1$  coefficients of the nonlinear elements [18]. With the  $Y$  matrix evaluated at mixing frequencies, the second-order port voltages are obtained by solving the following matrix equation:

$$[V_p(\omega_1, \omega_2)] = -[Y_{i=p,j=1,\dots,4}]^{-1} [I_{i=p,2}]^T, \quad p = 1, \dots, 4. \quad (16)$$

Similarly, third-order port voltages  $V_p(\omega_1, \omega_2, \omega_3)$  due to tone amplitudes  $V_{s1}$ ,  $V_{s2}$  and  $V_{s3}$  at frequencies  $\omega_1$ ,  $\omega_2$  and  $\omega_3$ , respectively, are calculated by using the first- and second-order port voltages and nonlinear coefficients  $p_1$  and  $p_2$ . The first-, second-, and third-order transfer functions are expressed as follows:

$$H_1(\omega_1) = V_4(\omega_1)/[V_{s1}Z_L(\omega_1)] \quad (17)$$

$$H_2(\omega_1, \omega_2) = 2 \frac{V_4(\omega_1, \omega_2)}{V_{s1}V_{s2}Z_L(\omega_1, \omega_2)} \quad (18)$$

$$H_3(\omega_1, \omega_2, \omega_3) = 4 \frac{V_4(\omega_1, \omega_2, \omega_3)}{V_{s1}V_{s2}V_{s3}Z_L(\omega_1, \omega_2, \omega_3)}. \quad (19)$$

With two equal amplitude tones at frequencies  $\omega_1$  and  $\omega_2$ , the third-order intermodulation components appear at  $2\omega_1 - \omega_2$  and  $2\omega_2 - \omega_1$ . The output power and third-order intermodulation distortion are as follows:

$$P_{out} = 0.5 |V_4(\omega_1)/Z_L(\omega_1)|^2 \text{Re}[Z_L(\omega_1)] \quad (20)$$

and

$$\text{IM3} = 20 \log_{10} \left[ \frac{3}{4} V_{s1} V_{s2} \frac{|H_3(\omega_1, \omega_1, -\omega_2)|}{|H_1(\omega_1)|} \right]. \quad (21)$$

### III. RESULTS AND DISCUSSION

Fig. 4 shows the calculated short-circuit current gain  $|h_{21}|$ , maximum stable gain (MSG), and maximum available gain (MAG) for a  $0.8 \mu\text{m} \times 150 \mu\text{m}$  GaN MESFET. The calculated results are compared with experimental data to show good agreement.  $|h_{21}|$  is 29 dB at 0.2 GHz and drops to 0 dB at 6.5 GHz, which corresponds to the unity gain current cutoff frequency  $f_T$ . MAG drops to 0 dB at 13 GHz and corresponds to the maximum frequency of oscillation  $f_{max}$  of the device. Inset shows the calculated  $f_T$  and  $f_{max}$  with increasing gate length. Experimental results for  $f_T$  are also plotted to show agreement. A steady increase in  $f_T$  for shorter gatelength devices is due to the increase in the overall transconductance along with a decrease in the gate–source and gate–drain capacitances.

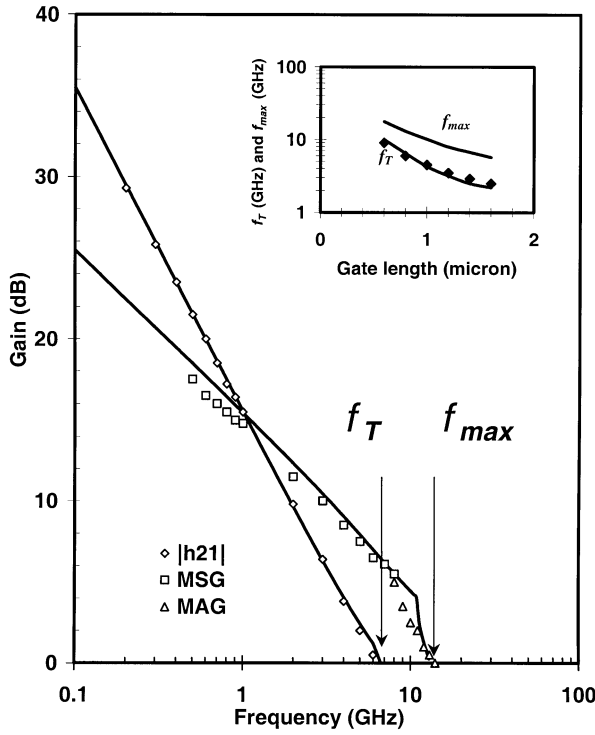


Fig. 4. Calculated (solid lines) and measured (symbol) short-circuit current gain  $|h_{21}|$ , MSG, and MAG of an  $0.8 \mu\text{m} \times 150 \mu\text{m}$  GaN MESFET. Inset shows the variation of  $f_T$  and  $f_{max}$  with gate length ( $V_{GS} = -4 \text{ V}$  and  $V_{DS} = 25 \text{ V}$ ) [12] (experimental data is shown by a symbol).

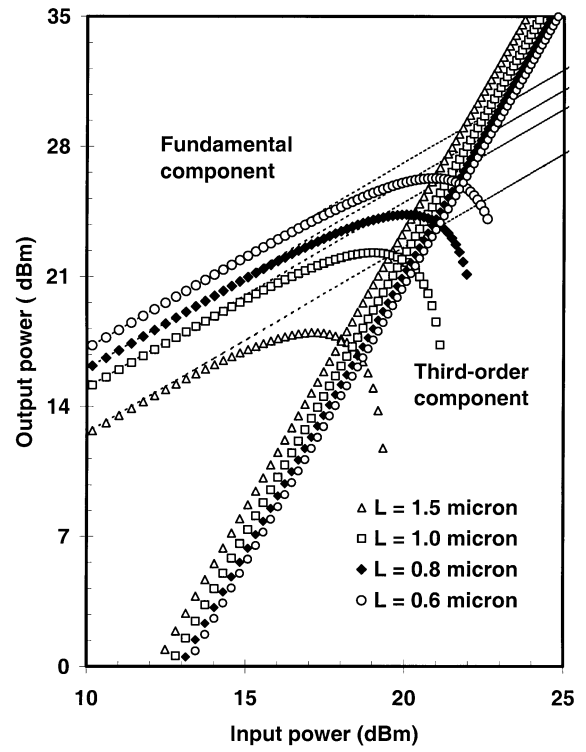


Fig. 5. Calculated fundamental and third-order components of output power of  $L \times 150 \mu\text{m}$  GaN MESFETs ( $V_{GS} = -4 \text{ V}$  and  $V_{DS} = 25 \text{ V}$ ) [12].

Fig. 5 shows the fundamental and third-order output powers as a function of input power with gate length as a parameter with tones at 1 and 1.01 GHz. The source and load resistances are  $50 \Omega$  each. With increasing input power, the fundamental component of the output power becomes sub-linear as the power delivered to the higher harmonics increases due to increasing device nonlinearity. The observed gatelength dependence is explained as follows. As shown in Table I, with decreasing gate length,  $g_{m0}$  increases and  $C_{gs0}$  decreases, which results in higher first-order transfer function  $|H_1(\omega_1)|$  of the device. Thus, for a given input power, the fundamental component of the output power increases for shorter lengths. However, with decreasing gate length, the third-order transfer function  $|H_3(\omega_1, \omega_1, -\omega_2)|$  decreases due to decreasing  $C_{gd}$ . Consequently, a lower third-order component of the output power is observed for shorter gatelength devices.

A 1-dB compression point ( $P_{1\text{-dB}}$ ) is referred to as the input power at which output power deviates from linearity by 1 dB. The OIP3 is defined as the output power at which the third-order intermodulation component of the output power intersects the fundamental component. Fig. 6. shows the variation of  $P_{1\text{-dB}}$  and OIP3 with increasing gate length.  $P_{1\text{-dB}}$  for a  $1.5\text{-}\mu\text{m}$  gatelength device is 16.3 dBm, which increases to 19.6 dBm for a MESFET with  $0.6\text{-}\mu\text{m}$  gate. The respective OIP3s are 22.2 and 30.5 dBm. These results are due to the significant improvement in device linearity for shorter gatelength devices. A similar result is reported for GaN/AlGaIn HEMTs [7].

Fig. 7 shows the third-order intermodulation distortion (i.e., IM3) as a function of output power for varying gate lengths with tones at 1 and 1.01 GHz. The source and load resistances are

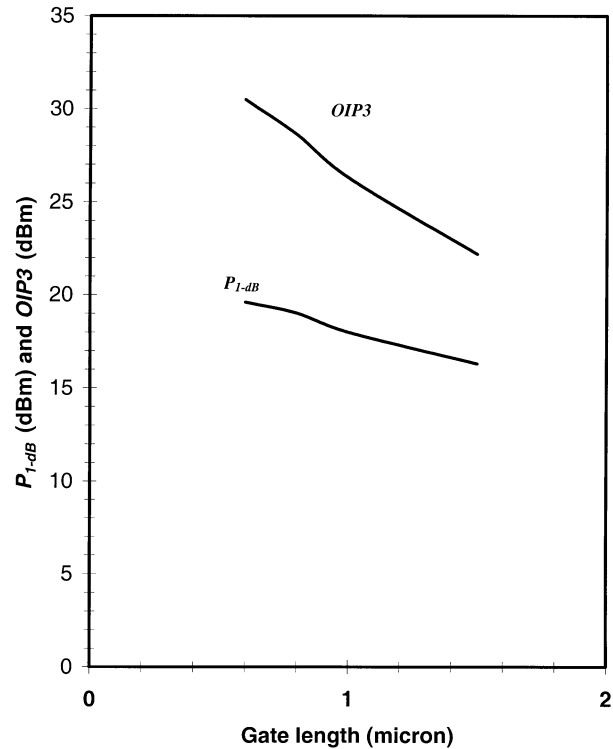


Fig. 6. 1-dB compression point ( $P_{1\text{-dB}}$ ) and OIP3 as a function of gate length ( $V_{GS} = -4 \text{ V}$  and  $V_{DS} = 25 \text{ V}$ ) [12].

$50 \Omega$  each. At 20-dBm output power, IM3 for a  $0.6\text{-}\mu\text{m}$  gatelength device is  $-30 \text{ dBc}$  and increases to  $-14.13 \text{ dBc}$  for the  $1.5\text{-}\mu\text{m}$  gatelength device. This is due to the improvement in device linearity for shorter gatelength devices, as explained above.

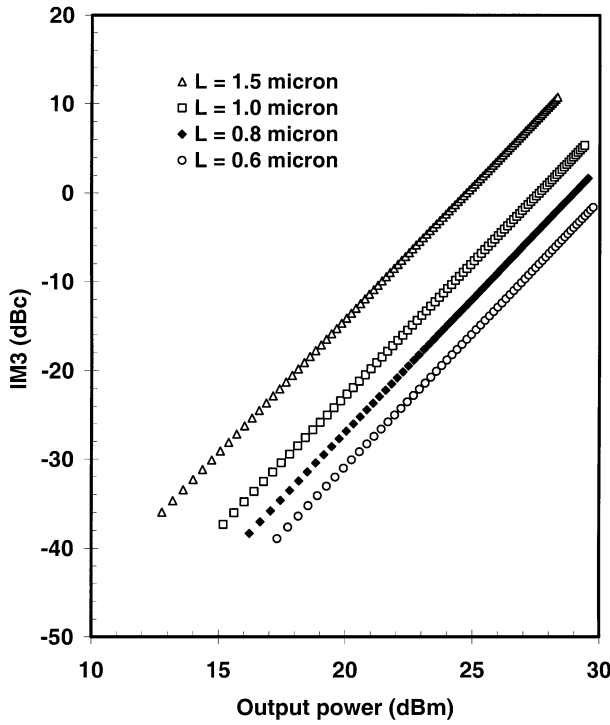


Fig. 7. IM3 as a function of output power of  $L \times 150 \mu\text{m}$  GaN MESFETs ( $V_{GS} = -4 \text{ V}$  and  $V_{DS} = 25 \text{ V}$ ) [12].

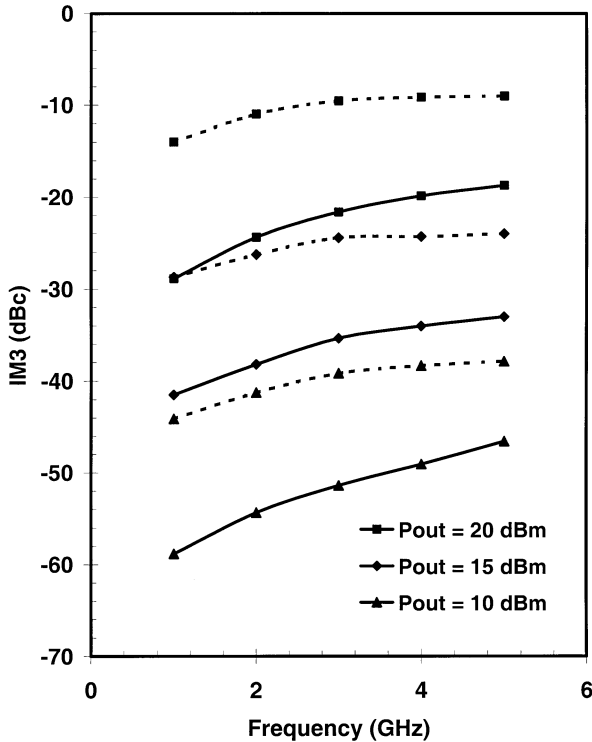


Fig. 8. IM3 as a function of frequency with output power as a parameter. Devices are  $0.6 \mu\text{m} \times 150 \mu\text{m}$  (solid lines) and  $1.5 \mu\text{m} \times 150 \mu\text{m}$  (dashed lines) GaN MESFETs ( $V_{GS} = -4 \text{ V}$  and  $V_{DS} = 25 \text{ V}$ ) [12].

Fig. 8 shows IM3 as a function of principal tone frequency with output power as a parameter. The second tone is assumed 10 MHz higher than the principal tone frequency. It is observed that IM3 increases with increasing frequency for a given output

power level. This is attributed to the third-order transfer function  $|H_3(\omega_1, \omega_1, -\omega_2)|$ , which increases with decreasing capacitive reactance due to  $C_{gd}$ , and the first-order transfer function  $|H_1(\omega_1)|$ , which decreases with decreasing capacitive reactance due to  $C_{gs0}$ , as evident from (21). Moreover, at a given frequency, IM3 increases with an increasing gate length and output power level. For structures with longer gate lengths, higher IM3 is obtained due to higher capacitances and lower transconductances (see Table I). At elevated output power levels, device nonlinearity increases, which results in higher IM3.

#### IV. CONCLUSION

Nonlinearities of GaN MESFETs are reported using a Volterra-series technique. A physics-based large-signal model is used to include the frequency dispersion of transconductance and output resistance due to the presence of traps. Calculated  $I$ - $V$  characteristics are in good agreement with experimental data. The calculated  $f_T$  and  $f_{max}$  are in excellent agreement with the experimental data. A significant improvement in device linearity is observed for shorter gatelength devices at lower operating frequencies.

#### APPENDIX

##### CIRCUIT PARAMETERS FOR THE TRAPPING RELATED SUB-NETWORK

The trapping sub-network parameters are given by [14], [15]

$$g_m'' = qv_{sat}WdN_{to}\alpha \left[ \frac{a_1 + 2a_2V_{GS}}{1 + a_1 + 2a_2V_{GS}} \right] \times \exp \left[ -\alpha (V_{DS} - V_{DS}^{ONSET}) \right]$$

$$R_{ds}'' \approx \frac{t_d}{C_{ss}(1 + g_{m2}R_{ds1})}$$

$$C_{ss} \approx C_{gs}$$

where  $V_{DS}^{ONSET} = a_0 + a_1V_{GS} + a_2V_{GS}^2$ ,  $a_0 = 6.24 \text{ V}$ ,  $a_1 = 1.29$ , and  $a_2 = 0.03 \text{ V}^{-1}$ .

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